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a relatively high level of abstraction, splitting robotics into four major areas seems reasonable: mechanical manipulation, locomotion, computer vision, and artificial intelligence. This book introduces the science and engineering of mechanical manipulation. This subdiscipline of robotics has its foundations in several classical fields. The major

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(In the sense of where the links of the robot are situated.) The answer is the robot's configuration: a specification of the positions of all points of the robot. Since the robot's links are rigid and of known shape, only a few numbers are needed to represent the robot's configuration.

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